

## PRS-202 SERIES

**High Precision  
Manual or Programmable  
Decade Resistance Substituters  
(IEEE-488.1)  
Operation Manual**



Copyright © 2011 IET Labs, Inc.

Effectivity: Serial Numbers prefixed E1 or higher  
PRS 202 im/October, 2011



**IET LABS, INC.**

534 Main Street, Westbury, NY 11590

[www.ietlabs.com](http://www.ietlabs.com)

TEL: (516) 334-5959 • (800) 899-8438 • FAX: (516) 334-5988

◆ PRECISION INSTRUMENTS FOR TEST AND MEASUREMENT ◆



---

**IET LABS, INC.**

534 Main Street, Westbury, NY 11590

www.ietlabs.com  
TEL: (516) 334-5959 • (800) 899-8438 • FAX: (516) 334-5988

## **WARRANTY**

We warrant that this product is free from defects in material and workmanship and, when properly used, will perform in accordance with applicable IET specifications. If within one year after original shipment, it is found not to meet this standard, it will be repaired or, at the option of IET, replaced at no charge when returned to IET. Changes in this product not approved by IET or application of voltages or currents greater than those allowed by the specifications shall void this warranty. IET shall not be liable for any indirect, special, or consequential damages, even if notice has been given to the possibility of such damages.

THIS WARRANTY IS IN LIEU OF ALL OTHER WARRANTIES, EXPRESSED OR IMPLIED, INCLUDING BUT NOT LIMITED TO, ANY IMPLIED WARRANTY OF MERCHANTABILITY OR FITNESS FOR ANY PARTICULAR PURPOSE.



## WARNING



OBSERVE ALL SAFETY RULES  
WHEN WORKING WITH HIGH VOLTAGES OR LINE VOLTAGES.

**Dangerous voltages may be present inside this instrument. Do not open the case  
Refer servicing to qualified personnel**

### **HIGH VOLTAGES MAY BE PRESENT AT THE TERMINALS OF THIS INSTRUMENT**

WHENEVER HAZARDOUS VOLTAGES (> 45 V) ARE USED, TAKE ALL MEASURES TO  
AVOID ACCIDENTAL CONTACT WITH ANY LIVE COMPONENTS.

USE MAXIMUM INSULATION AND MINIMIZE THE USE OF BARE  
CONDUCTORS WHEN USING THIS INSTRUMENT.

**Use extreme caution when working with bare conductors or bus bars.**

WHEN WORKING WITH HIGH VOLTAGES, POST WARNING SIGNS AND  
KEEP UNREQUIRED PERSONNEL SAFELY AWAY.



## CAUTION



DO NOT APPLY ANY VOLTAGES OR CURRENTS TO THE TERMINALS OF THIS  
INSTRUMENT IN EXCESS OF THE MAXIMUM LIMITS INDICATED ON  
THE FRONT PANEL OR THE OPERATING GUIDE LABEL.

# CONTENTS

<b>WARRANTY</b> .....	<b>i</b>
<b>WARNING</b> .....	<b>ii</b>
<b>CAUTION</b> .....	<b>ii</b>
<b>CONTENTS</b> .....	<b>iii</b>
<b>FIGURES</b> .....	<b>iv</b>
<b>TABLES</b> .....	<b>iv</b>
<b>Chapter 1: INTRODUCTION</b> .....	<b>1</b>
<b>Chapter 2: SPECIFICATIONS</b> .....	<b>3</b>
2.1 Model Configuration and specifications .....	3
2.2 General specifications .....	4
<b>Chapter 3: OPERATION</b> .....	<b>6</b>
3.1 Initial inspection and setup .....	6
3.2 Connection .....	6
3.2.1 General Considerations .....	6
3.2.2 Electrical Considerations .....	6
3.2.3 Four-Wire Kelvin Lead Connections .....	6
3.2.4 Thermal emf Considerations .....	6
3.3 Dial Setting .....	7
3.4 Environmental Conditions .....	7
3.5 Local Operation .....	7
3.6 Remote Operation .....	7
<b>Chapter 4: BCD INTERFACE OPTION</b> .....	<b>8</b>
4.1 BCD Programming .....	8
<b>Chapter 5: IEEE-488 PROGRAMING</b> .....	<b>10</b>
5.1 Introduction .....	10
5.2 Capabilities .....	10
5.3 Address Switch Settings .....	10
5.3.1 Bus Set-Up Procedure .....	11
5.4 Controlling the Programmable Impedance Substituter .....	11
5.4.1 Preparation .....	11
5.4.2 Command String Structure .....	11
5.5 Testing and Programming .....	12
5.5.1 GPIB Test Keyboard .....	12
5.5.2 DOS Programming (Legacy) .....	13
<b>Chapter 6: MAINTENANCE</b> .....	<b>15</b>
6.1 Verification of Performance .....	15
6.1.1 Calibration Interval .....	15
6.1.2 General Considerations .....	15

## Figures

Figure 1.1 High Precision Manual or Programmable Decade Resistance Substituter ....	1
Figure 2.1 Typical OPERATING GUIDE Affixed to Unit .....	5

## Tables

Table 4.1 BCD INPUT Connector .....	8
Table 4.2 BCD INPUT Connector Pin Assignments .....	9
Table 5.1 IEE-488 Bus Functions .....	10
Table 5.2 Bus Address Switch Settings .....	11

# Chapter 1

## INTRODUCTION

The PRS Series (Figure 1.1) is a broad line of high precision manual and programmable decade substituters. They provide direct resistance substitution as well as RTD (Resistance Temperature Detector) simulation, in a wide selection of ranges, tolerances and ratings.

The PRS substituter is a precision resistance source with excellent characteristics of stability, temperature coefficient, and power coefficient. High dynamic ranges are available, starting as low as 1 m $\Omega$ , and extending to as many as 10 decades. These features combined with a low virtually constant “zero resistance” make for very versatile instruments.

The PRS Series features two optional special settings. An “open circuit” and a “short circuit”. These modes are useful for obtaining reproducible transitions between settings, i.e. break-before-make or to short between settings. The “short circuit” setting also provides a reduced zero resistance.

Operation is both local using convenient direct-reading front panel thumbwheel switches, and remote with optional parallel BCD, RS-232, or IEEE-488 interfaces. Both can provide an optional extra “10” position for each decade.

The PRS Series employs very low resistance, low thermal emf relays with gold-clad silver-alloy contacts. A special design keeps contact resistance to a minimum. The gold plating keeps the silver contacts from becoming tarnished when unused, or when only

low currents are passed through them. This is most often the case when only minute test currents are drawn by digital multimeters and other test instruments. Contact resistance remains low and repeatable.

High-quality gold-plated tellurium-copper five-way binding posts serve to minimize the thermal emf effects, which would produce errors in dc resistance measurements. All other conductors within the instrument, as well as the solder employed contain no metals or junctions that could contribute to thermal emf problems.

With a resolution as low as 1 m $\Omega$  and a maximum available resistance of over 100 M $\Omega$ , the PRS-202 Series may be used for exacting precision measurement applications requiring high accuracy, good stability, and low zero resistance. They are suited for automatic and manual calibration and testing, simulation of RTD'S, programmable loads, and many other laboratory and industrial applications.

The PRS Series may be rack mounted to serve as components in measurement and control systems.



**Figure 1.1: High Precision Manual or Programmable Decade Resistance Substituter**

This page is intentionally left blank.

### PRS-202 SERIES OPERATING GUIDE

CONSULT INSTRUCTION MANUAL FOR PROPER INSTRUMENT OPERATION

<b>Resistance Type:</b>	Resistance wire for 0.1 $\Omega$ steps and under; hermetically sealed wirewound, low inductance resistors for 1 $\Omega$ and over.	
<b>Range:</b>	0 to 999,999.9 $\Omega$ , with 0.1 $\Omega$ resolution.	
<b>Accuracy:</b>	$\pm(0.02\% + 5 \text{ m}\Omega)$ , after subtraction of "zero resistance", at 23°C; traceable to NIST.	
<b>Zero Resistance:</b>	<100 m $\Omega$ .	
<b>Drift after Warm-up:</b>	< $\pm(75 \text{ ppm} + 2 \text{ m}\Omega)$ , true resistance drift.	
<b>Maximum Load:</b>	3 A, or 200 V (dc + ac peak), or 0.5 W/step, or 4.5 W maximum, whichever applies first.	
<b>Interface:</b>	IEEE-488-1978; front panel switch selects <b>REMOTE</b> (digital interface) or <b>LOCAL</b> (front panel thumbwheel) operation.	
<b>Terminals:</b>	Four gold plated tellurium copper binding posts are provided for <b>HI</b> and <b>LO</b> terminal pairs for <b>CURRENT</b> and <b>SENSE</b> . These binding posts virtually eliminate thermal emf effects at their junctions. One additional binding post, <b>GND</b> , is connected to the case, to chassis ground, and to earth ground.	

  

<b>POWER:</b> <u>110-125 V or 210-250 V</u> (internally switch selectable) 50-60 Hz; 30 W max; 0.5 A fuse, 5x20 mm	<b>MODEL:</b> <u>PRS-Q-7-.1-IEEE</u> <b>SN:</b> <u>D6-0107189</u>
---	--

  



**WARNING**

**Observe all safety rules when working with high voltages or line voltages.**

ELECTRICAL SHOCK HAZARD. DO NOT OPEN CASE.  
REFER SERVICING TO QUALIFIED PERSONNEL.



  



**IET LABS, INC.** • 534 Main Street, Westbury, NY 11590 • (800) 899-8438

CAGE CODE: 62015      [www.ietlabs.com](http://www.ietlabs.com)

PRS202BLBL/p22/PRS-Q-7-0.1/70%02-01

Figure 2.1 Typical OPERATING GUIDE Affixed to Unit

# Chapter 3

## OPERATION

### 3.1 Initial inspection and setup

This instrument was tested and carefully inspected before shipment. It should be in proper electrical and mechanical order upon receipt.

An **OPERATING GUIDE** is attached to the case of the instrument to provide ready reference to specifications.

Mount the unit in a standard 19" rack if the rack mount option is specified.

### 3.2 Connection

#### 3.2.1 General Considerations

The PRS Series Decade unit is built in 3-terminal or 5-terminal versions. The binding posts are standard laboratory type and readily accept banana plugs, telephone tips, spade lugs, alligator clips, and bare wire. Binding posts are located on the front panel of the instrument unless specifically ordered with a Rear Output option.

The 3-terminal version posts are labeled **HI**, **LO**, and **GND**. The **HI** and **LO** terminals are connected to the ends of the internal impedance being set.

5-terminal models provide four Kelvin terminals consisting of a **CURRENT** and a **SENSE** pair, each labeled **HI** and **LO**. These minimize contact resistance.

The **GND** terminal on all models is connected to the case and to earth and chassis grounds. This may be used as a shield terminal.

#### 3.2.2 Electrical Considerations

The performance of the PRS is directly affected by the quality of the connection to the system under test. This is particularly true with the precision series models having higher-accuracy and/or lower-impedance decades.

For optimum performance, contact resistance should be kept to a minimum by using the most substantial mating connection possible, and by assuring that the connection is well secured to the binding posts.

#### 3.2.3 Four-Wire Kelvin Lead Connections

4-wire Kelvin leads minimize the effects of contact resistance and approach ideal performance. The **CURRENT** and **SENSE HI/LO** terminal pairs may be shorted together to provide a 2-terminal connection in instances where high accuracy is not a concern.

#### 3.2.4 Thermal emf Considerations

The PRS Series uses high-quality, low-emf components. Thermal emf is primarily attributable to the temperature difference between the leads of the relay and the contacts when temperature is applied to the coil. This emf is of the order of 5  $\mu\text{V}$  per relay, but is not usually additive. The typical worst case is <15  $\mu\text{V}$ .

PRS-202 IEEE.2/05-12-05

If the effect of tens of microvolts is significant to your application, connect to the instrument with low-thermal-emf materials only. Copper wire and copper alloys are recommended; brass and steel should be avoided. Tinned copper and solder are acceptable.

This emf will *not* be reflected if an ac measurement instrument is employed, and can be eliminated by using a meter with “True Ohm” capability. In other cases, the emf may represent a very small component of a dc resistance measurement.

### 3.3 Dial Setting

Each decade is manually controlled via a front panel thumbwheel that provides positions for “0” through “9”. The total impedance is set/read directly from the dial setting. The decimal point, if any, is marked on the thumbwheel switches, and the steps are clearly marked on the panel. Short Circuit / Open Circuit mode control is only available using a Remote control option.

### 3.4 Environmental Conditions

The PRS is built, calibrated and intended for use in a laboratory environment with a nominal ambient temperature near 23°C. The accuracy of the unit may be affected when operated in non-laboratory environments. Always allow the instrument to stabilize at room temperature after unpacking or relocating the instrument. Humidity should be maintained at laboratory conditions.

### 3.5 Local Operation

Operation of the PRS substituter is straightforward and graphically represented on the front panel.

1. Turn on the **POWER** switch. The **POWER** indicator lamp, if present, should come on. If a **REMOTE** option is present, the **READY** and **LOCAL** indicators should illuminate.
2. Set the **REMOTE/LOCAL** switch to **LOCAL**.

3. Connect any desired instrumentation to the front panel binding posts. The **GND** terminal may be connected to the ground of external equipment. The **GND** terminal is connected to the case and to both chassis and earth grounds.
4. Make 4-terminal or 2-terminal connections as described previously. A shielded set of cables is recommended whenever ac operation or high resistance are involved.
5. Set the thumbwheel switches to provide the desired impedance in the units indicated on the front panel.

### 3.6 Remote Operation

The PRS includes a **REMOTE/LOCAL** switch on the front panel. The **REMOTE** position is a remote *enable*. When in **LOCAL** mode, the PRS supplies the impedance value selected using the front panel thumbwheel switches.

When the switch is in the **REMOTE** position, the PRS will supply the configured remote impedance value *only if* that option asserts remote control. If the option does not assert control, the front panel thumbwheel impedance value is supplied. The **REMOTE** and **LOCAL LEDs** always indicate which interface is controlling the impedance value.

Setting the front panel **REMOTE/LOCAL** switch to **LOCAL** *overrides* the **REMOTE** option settings and *always* sets the supplied impedance to the value selected using the front panel thumbwheels, regardless of the **REMOTE** option’s assertion of control. The **REMOTE BCD** option sets impedance values and asserts control using TTL logic. The impedance values are BCD encoded as shown in table 4.2.

For IEEE and RS232 units, the **LOCAL** indicator remains on until communication with the unit is initialized. The mode changes to **REMOTE** after controller commands are received.

## Chapter 4

# BCD INTERFACE OPTION

### 4.1 BCD Programming

PRS units, with BCD interface option, come with a **BCD (Binary Coded Decimal, 1-2-4-8 coding)** remote programming capability accessed through the **BCD INPUT** connector

The connector is a 50-pin, female, parallel-interface industry-standard connector found on the rear panel. Table 4.1 shows the connector pin numbering. Table 4.2 gives the pin assignments for the BCD input for this connector. There can be as many as 10 digits to be input. For any unit with fewer than 10 digits, only the implemented subset of these will be operational. All other digits may be ignored, and the associated pins may be left open or shorted to ground.

Once the unit is switched to **REMOTE** with the front panel knob, it may be set to either **LOCAL** or **REMOTE** states under external control by properly selecting pins 21 and 22 on the **BCD INPUT** rear panel

connector as shown in Table 4.1. Note that both pins must be set. The **REMOTE** and **LOCAL** led's will respond accordingly. Once the PRS is set to **Remote**, the thumbwheel switches become disabled, and impedance control is transferred to the rear panel connector.

In addition, two special optional function pins are provided to set the unit to Open-circuit or (optional) Short-circuit states across the **HI** and **LO** terminals on the front panel. Applying a low to pin 34 activates an open circuit condition. If the short circuit option is present (this option provides a lower resistance short circuit than a zero setting), applying a high to pin 35 provides a short circuit. If these functions are not required, these two pins may be left open, or the opposite logic levels may be applied, i.e. high to pin 34 and low to pin 35. If both pins are activated, the system will be in the short-circuit mode. If the short-circuit option is not present, pin 20 may be left in any state.

<b>25</b>	<b>24</b>	.....	<b>2</b>	<b>1</b>
<b>50</b>	<b>49</b>	.....	<b>27</b>	<b>26</b>

(Viewed from rear of instrument)

**Table 4.1 BCD INPUT Connector**

Pin No.	BCD Code Weight	Function	Description
30	1		
31	2		
32	4		0.01-0.09Ω
33	8		
43	1		
42	2		
41	4		0.1-0.9 Ω
40	8		
39	1		
38	2		
37	4		1-9 Ω
36	8		
47	1		
46	2		
45	4		10-90 Ω
44	8		
4	1		
3	2		
2	4		100-900 Ω
1	8		
8	1		
7	2		
6	4		1-9 kΩ
5	8		
12	1		
11	2		
10	4		10-90 kΩ
9	8		
16	1		
15	2		
14	4		100-900 kΩ
13	8		
20	1		
19	2		
18	4		1-9 M Ω
17	8		
29	1		
28	2		
27	4		10-90 M Ω
26	8		
34		Open-circuit control	Low to activate; otherwise high or open.
35		Short-circuit control (optional)	High to activate; otherwise low or open; If option is absent, pin may be in any state.
23		Earth ground	
24		+5V, 10 mA maximum	
25		Earth ground	
21		LOCAL/REMOTE select	High for LOCAL; Low for REMOTE
22		LOCAL/REMOTE select	Low for LOCAL; High for REMOTE
48		Reserved for IEEE-488	
49		Reserved for IEEE-488	
50		Reserved for IEEE-488	

**Table 4.2 BCD INPUT Connector Pin Assignments**

## Chapter 5

# IEEE-488 PROGRAMMING

### 5.1 Introduction

The IEEE-488 Interface converts the PRS-200 Series Programmable Impedance Substituter into an instrument compatible with the standard IEEE-488-1978 interface bus. This capability allows the PRS-200 instrument to become part of a fully automated instrumentation system.

If necessary, it is strongly recommended that the user refer to documentation for background on the operation of this interface. In particular, the standard is available on-line at <http://www.ieee.org>.

Other tutorials are available on-line; consult IET for additional information. A software GPIB “keyboard” may be requested from IET to perform elementary commands for training and testing. See Section 5.5.1

### 5.2 Capabilities

The IEEE-488 interface provides remote control over all of the front panel functions except for the **POWER** switch. Table 5.1 lists the particular IEEE-488 capabilities implemented in this unit.



Figure 5-1: Bus Address Switch

### 5.3 Address Switch Settings

Each GPIB bus device is identified by a five-bit binary address. There are 32 possible primary addresses 0 through 31; addresses 0 and 31 are reserved. The PRS **BUS ADDRESS** switch shown in Figure 5-1 establishes the GPIB address of the unit. Bus address settings are read at power up. Refer to table 5.1.

The T-L-S positions on the **BUS ADDRESS** switch are not used and should remain in the “OFF” position.

Table 5.1 IEEE-488 Bus Functions

Code	Description	Comments
SR0	Source Handshake	Not implemented
AHI	Acceptor Handshake	Included
RL1	Remote, Local	Included
SR0	Service Request	Not implemented
T0	Talker	Not implemented
TE0	Extended Talker	Not implemented
LI	Listener	Included
LE0	Extended Listener	Not implemented
PP0	Parallel Poll	Not implemented
DC1	Device Clear	Included
DT0	Device Trigger	Not implemented
C0	Controller	Not implemented

**Table 5.2 Bus Address Switch Settings**

Decimal Address	SWITCH SETTINGS 5-4-3-2-1	Decimal Address	SWITCH SETTINGS 5-4-3-2-1
0	0-0-0-0-0	16	1-0-0-0-0
1	0-0-0-0-1	17	1-0-0-0-1
2	0-0-0-1-0	18	1-0-0-1-0
3	0-0-0-1-1	19	1-0-0-1-1
4	0-0-1-0-0	20	1-0-1-0-0
5	0-0-1-0-1	21	1-0-1-0-1
6	0-0-1-1-0	22	1-0-1-1-0
7	0-0-1-1-1	23	1-0-1-1-1
8	0-1-0-0-0	24	1-1-0-0-0
9	0-1-0-0-1	25	1-1-0-0-1
10	0-1-0-1-0	26	1-1-0-1-0
11	0-1-0-1-1	27	1-1-0-1-1
12	0-1-1-0-0	28	1-1-1-0-0
13	0-1-1-0-1	29	1-1-1-0-1
14	0-1-1-1-0	30	1-1-1-1-0
15	0-1-1-1-1	31	Reserved, do not use

### 5.3.1 Bus Set-Up Procedure

1. Turn off the **POWER** switch.
2. Set the **BUS ADDRESS** switch as described above.
3. Turn on the **POWER** switch. This allows the unit to read the status of the rear panel **BUS ADDRESS** switch settings. They can only be read at turn on, so if they need to be changed, the unit must be reinitialized by being momentarily turned off.
4. The **READY** indicator lamp on the front panel should come on with turn on.

## 5.4 Controlling the Programmable Impedance Substituter

### 5.4.1 Preparation

After performing any necessary initialization related to the controller in the system, proceed as follows:

1. Set the PRS-200 unit to **LISTEN** using its pre-set address. The **LISTEN** indicator lamp on the front panel should come on.
2. Set the PRS-200 to **REMOTE** using its pre-set address. The **REMOTE** indicator lamp on the front panel should come on.
3. Output a command string as described below.

### 5.4.2 Command String Structure

The command string to the PRS-200 unit is in the form of an (n+1) character string where n is the number of decades on the front panel thumbwheel switches. This number is constructed as the following concatenation:

**|Mode Command Digit|n character Impedance Command|**

The Mode Command Digit is required only whenever it is desired to activate the optional OPEN CIRCUIT or SHORT CIRCUIT modes; otherwise it is not required.

For a device having neither option, the least significant characters up to a maximum of n are read as a command; the Mode Command Digit or any other additional characters to the 'left' or on the most significant end of the string are ignored by the device.

Whenever there are leading zeroes in the command, the command string in all cases can be shorter than n.

**Mode Command Digit =**

- 0, 4, 8, or absent for NORMAL operation**
- 1, 5, or 9 for OPEN CIRCUIT operation -optional**
- 2, 3, 6, or 7 for SHORT CIRCUIT operation -optional**
- X or absent for units without either option**

**Impedance Command =**

- 1 to n characters (0-9) for impedance value;**
- n characters (with leading zeros if necessary) are required if the Mode Command Digit is being transmitted.**

This Impedance Command must be provided as an ASCII string made up of the characters "0"- "9", representing the digits 0-9 or HEX 30-39 respectively.

For example, the command strings for the following resistance settings for a unit with 7 decades and 1  $\Omega$  minimum steps are as follows:

<b>100 <math>\Omega</math></b>	<b>100 or 0100 or 00100 or 000100 or 0000100</b>
<b>600567 <math>\Omega</math></b>	<b>600567</b>
<b>Open circuit</b>	<b>1XY.XXY-X where X represents any digit</b>
<b>Short circuit</b>	<b>2XXXXXX where X represents any digit</b>

For a second example, the command strings for the following resistance settings for a unit with 5 decades and .01  $\Omega$  minimum steps are as follows:

<b>.99 <math>\Omega</math></b>	<b>99 or 099 or 0099 or 00099 or 00.99, etc.</b> (decimal point is ignored)
<b>100.00 <math>\Omega</math></b>	<b>10000</b>
<b>231.05 <math>\Omega</math></b>	<b>23105 or 231.05 (decimal point is ignored)</b>
<b>Open circuit</b>	<b>1XXXXXX where X represents any digit</b>
<b>Short circuit</b>	<b>2XXXXXX where X represents any digit</b>

The command string may be output with or without leading zeros in the normal, i.e. non short or open circuit modes.

This command string must be followed by an appropriate terminator such as a **CR** (carriage return), **LF** (line feed), comma, or the presence of an **EOI** signal on the bus which will terminate the listen message.

If there is a decimal point on the thumbwheel switches, this decimal point may be optionally included in the command string.

In the optional Open circuit and Short circuit modes, the n character Impedance Command must be given in full including all leading zeros. The relays will be set as commanded although these values will be overridden by the short or open circuit modes. This feature however may be used to provide a controlled transition between two resistance values without being concerned by the indeterminate transitional switching of the various relays. This is done as follows to change from resistance R1 to resistance R2:

1. Output a command for R1.
2. Output a command for R1 plus a short circuit Mode Command digit.
3. Output a command for R2 plus a short circuit Mode Command digit.

4. Output a command for R2.

Clearly the above example would also apply for the Open circuit mode.

Illegal characters in the command string will be ignored except for HEX 3B-3F which will result in an open circuit or an erroneous resistance setting, depending on the particular model configuration. If an open circuit is desired, these characters may be tested to determine if they produce an open circuit, or IET may be consulted.

## 5.5 Testing and Programming

### 5.5.1 GPIB Test Keyboard

To aid the user in operating the PRS-200, a GPIB “Keyboard” Controller program - the easiest way to control GPIB devices without writing a program - is available from IET. This GPIB Keyboard program automatically finds your device at startup and it lets you enter just the data that you want to send to the device. This program works with ICS, Measurement Computing and National Instruments controllers.

To implement, request from IET Labs Tech Support a download of **ICS\_GPIBkybd\_Install.zip**.

Unzip the file and follow instructions to install.

Open the application. You may use the **Find Listeners** button to confirm that the PRS unit is recognized. Other instruments may also be recognized at this time. Enter and set the address to the PRS address. Use the window to send commands to the PRS as follows

#### **PO resistance string**

where the resistance string is constructed as described above in Section 4.4.2.

### 5.5.2 DOS Programming (Legacy)

A sample BASIC program is given on the following page. It is used by a MetraByte Corporation Model MBC-488 Controller Board.

This program first initializes the controller, then sets the device to the **REMOTE** and **LISTEN** modes, then outputs a command string provided by the operator to the device, and finally sets the device to the **LOCAL** mode. Note that the variable BA0% refers to the controller board number.

```

100 *****
110 '*   SAMPLE PRS-200 SERIES IEEE-488 COMMAND PROGRAM           *
120 '*                                                                 *
130 '* MX3                                                         *
140 *****
150 CLEAR 20000, 40000!
160 CLS : KEY OFF
170 '
180 'This program let's you write a device dependent command string
190 'to any device number.
200 '
210 '---- Load link that calls DOS resident driver (REMOVE IF COMPILED)
220 '
230 DEF SEG = &H3600
240 BLOAD "GPIBBASI.BIN", 0
250 IE488 = 0
260 '
270 '----- Initialize MBC-488 board using "SYSCON" command
280 '
290 CMD$ = "SYSCON MAD=3, CIC=1, NOB=1, BA0=&H300" 'change to suit
300 A% = 0: FLAG% = 0: BRD% = 0
310 CALL IE488(CMD$, A%, FLAG%, BRD%)   'initialize
320 IF FLAG% <> 0 THEN PRINT "Error #"; HEX$(FLAG%); " in initialization": STOP
330 '
340 INPUT "Enter device number: ", DN
350 '
360 '----- Set device into REMOTE -----
370 CMD$ = "REMOTE " + STR$(DN)
380 CALL IE488(CMD$, A%, FLAG%, BRD%)
390 IF FLAG% <> 0 THEN PRINT "Error in setting to remote. Error code "; HEX$(FLAG%): INPUT "Con-
400 '
410 '----- Send command to device -----
420 '
430 PRINT : INPUT "(type 'Q' to quit) Enter device command string: ", X$
435 IF X$ = "Q" THEN 530 ELSE IF X$ = "" THEN 430
440 CMD$ = "OUTPUT " + STR$(DN) + "["$
450 CALL IE488(CMD$, X$, FLAG%, BRD%)
460 IF FLAG% <> 0 THEN PRINT "Error in output of command. Error code "; HEX$(FLAG%): INPUT
470 GOTO 350
530 RUN "MENUV"

```

# Chapter 6

## MAINTENANCE

### 6.1 Verification of Performance

#### 6.1.1 Calibration Interval

The PRS Series instruments should be verified for performance at a calibration interval of twelve (12) months. This procedure may be carried out by the user, if a calibration capability is available, by IET Labs, or by a certified calibration laboratory. If the user should choose to perform this procedure, then the considerations below should be observed.

#### 6.1.2 General Considerations

It is important, whenever testing the PRS Series Decade units, to be very aware of the capabilities and limitations of the test instruments used. Such instruments have to be significantly more accurate than the specified accuracy for all applicable ranges in order to perform this task, allowing for a band of uncertainty of the instrument itself, the test setup and the environment; consult IET Labs for information.

It is important to allow both the testing instrument and the PRS Substituter to stabilize for a number of hours at the nominal operating temperature of 23°C, and at nominal laboratory conditions of humidity. There should be no temperature gradients across the unit under test.

In the case of a resistance substituter, substantial Kelvin type 4-wire test terminals should be used to obtain accurate low-resistance readings. It is convenient, once the zero-resistance has been determined, to subtract it from the remaining measurements. This can be done automatically in many instruments which have an offset subtraction capability.

Steps should be taken to minimize thermal-emf effects, by maintaining an even temperature and by using only low-emf connectors. Use of meters with a “True Ohm” function is recommended.

Proper metrology practices should be followed in performing this verification.

